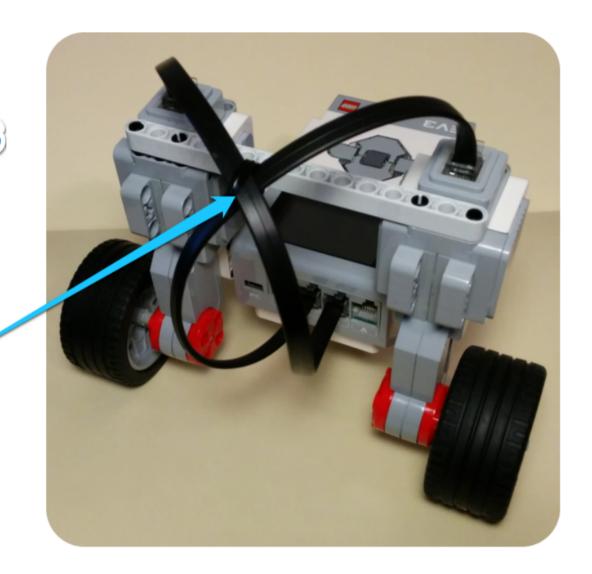


## Plug in the Motor Cables

One into 'B'
One into 'C'

Make sure they crossover



## **Grabber Attachment**

